

# Involutive Bases II

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Overview

Basic Computational  
Problems

Continuous and  
Constructive Divisions

Monomial Completion

Polynomial Completion

Minimal Bases

Optimisations and  
Complexity Issues

- **General Involutive Bases**
- **Basic Algorithms**
  - Continuous and Constructive Divisions
  - Monomial Completion
  - Polynomial Completion
  - Minimal Bases and Optimisations
- **Pommaret Bases and  $\delta$ -Regularity**
- **Combinatorial Decompositions and Applications**
- **Syzygy Theory and Applications**

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## ■ existence of **finite** involutive basis

- clear for Noetherian division via Gröbner bases...
- ... but recall counterexample for Pommaret division

## ■ **effective** criterion for involutive basis

- basic theory provides *no* finite test
- need “substitute” for  $S$ -polynomials
- where lies “*first*” obstruction to involution?

## ■ **algorithmic** construction of involutive basis

- non-trivial already in *monomial* case!
- “reduced” basis — uniqueness?

## ■ **efficient** algorithms

- optimisations
- heuristics

# Continuous and Constructive Divisions

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**Idea:** consider only “*nearest*” obstruction to involution  $\rightsquigarrow$   
multiply with a *single* non-multiplicative variable

**Def:** finite set  $\mathcal{T} \subset \mathbb{T}(X)$  *locally involutive*  $\rightsquigarrow$

$$\forall t \in \mathcal{T}, y \in \bar{X}_{L,\mathcal{T}}(t) : yt \in \langle \mathcal{T} \rangle_L$$

(here:  $\bar{X}_{L,\mathcal{T}}(t) = X \setminus X_{L,\mathcal{T}}(t)$  set of *non-multiplicative* variables)

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(here:  $\bar{X}_{L,\mathcal{T}}(t) = X \setminus X_{L,\mathcal{T}}(t)$  set of *non-multiplicative* variables)

obviously:  $\mathcal{T}$  involutive  $\implies$   $\mathcal{T}$  locally involutive

what about the converse?

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**Example:** recall bizarre global division on  $\mathbb{T}(x, y, z)$  defined in Lecture I by the following set of multiplicative variables

$$\begin{aligned}X_L(1) &= \{x, y, z\} \\X_L(x) &= \{x, z\}, \quad X_L(y) = \{x, y\}, \quad X_L(z) = \{y, z\}, \\X_L(t) &= \emptyset \text{ for all other } t \in \mathbb{T}(x, y, z)\end{aligned}$$

Consider the set  $\mathcal{T} = \{x, y, z\}$

■  $\mathcal{T}$  locally involutive

$$y \cdot x = x \cdot y \quad z \cdot y = y \cdot z \quad x \cdot z = z \cdot x$$

■ But  $\mathcal{T}$  not involutive:  $xyz \in \langle \mathcal{T} \rangle \setminus \langle \mathcal{T} \rangle_L$

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**Def:** involutive division  $L$  *continuous*  $\rightsquigarrow$

$\forall$  finite sets  $\mathcal{T} \subset \mathbb{T}(X)$   $\forall$  finite sequences  $(t_1, \dots, t_r)$   
with  $t_i \in \mathcal{T}$  and  $\forall t_i \exists y_i \in \bar{X}_{L, \mathcal{T}}(t_i) : t_{i+1} \mid_{L, \mathcal{T}} y_i t_i$

$\forall k \neq \ell : t_k \neq t_\ell$

(in other words: such sequences cannot be *cyclic*)

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**Prop:**  $L$  continuous,  $\mathcal{T}$  locally involutive  $\implies \mathcal{T}$  involutive

(provides us with *finite* criterion for involutive sets!)



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**Prop:**  $L$  continuous,  $\mathcal{T}$  locally involutive  $\implies \mathcal{T}$  involutive

(provides us with *finite* criterion for involutive sets!)

**Proof:** (quite technical)

assume existence of *minimal* obstruction to involution  $x^\mu$  not of form  $yt$ ;  
starting from divisor  $t \in \mathcal{T}$  of  $x^\mu$ , construct infinite sequence contradicting  
continuity of division  $L$

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**Prop:**  $L$  continuous,  $\mathcal{T}$  locally involutive  $\implies \mathcal{T}$  involutive

(provides us with *finite* criterion for involutive sets!)

**Lemma:** Janet and Pommaret division continuous

**Proof:** sequence ascending in appropriate sense

Janet division  $\rightsquigarrow \prec_{\text{lex}}$

Pommaret division  $\rightsquigarrow$  “essentially”  $\prec_{\text{revlex}}$

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**Problem:** continuity still not sufficient for design of effective algorithm  $\rightsquigarrow$   
need further very technical property (developed by “reverse engineering”)

**Def:** continuous division  $L$  *constructive*  $\rightsquigarrow$

$\forall \mathcal{T} \subset \mathbb{T}(X)$  finite,  $t \in \mathcal{T}$ ,  $y \in \bar{X}_{L,\mathcal{T}}(t)$  such that

(i)  $yt \notin \langle \mathcal{T} \rangle_L$

(ii) if  $\exists s \in \mathcal{T}$ ,  $z \in \bar{X}_{L,\mathcal{T}}(s) : zs \mid yt \wedge zs \neq yt$ , then  $zs \in \langle \mathcal{T} \rangle_L$

$\nexists r \in \langle \mathcal{T} \rangle_L : yt \in \mathcal{C}_{L,\mathcal{T} \cup \{r\}}(r)$

(underlying **idea:** it makes no sense in a completion process to add elements already contained in the involutive span)

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**Lemma:** Janet and any continuous global division constructive

**Proof:** simple for global division; very technical for Janet division

## Basic monomial completion algorithm

**Input:** finite set  $\mathcal{T} \subset \mathbb{T}(X)$ , involutive division  $L$

**Output:** weakly involutive completion  $\hat{\mathcal{T}}$  of  $\mathcal{T}$

- 1:  $\hat{\mathcal{T}} \leftarrow \mathcal{T}$
- 2: **loop**
- 3:  $\mathcal{S} \leftarrow \left\{ yt \mid t \in \hat{\mathcal{T}}, y \in \bar{X}_{L, \hat{\mathcal{T}}}(t), yt \notin \langle \hat{\mathcal{T}} \rangle_L \right\}$
- 4: **if**  $\mathcal{S} = \emptyset$  **then**
- 5:     **return**  $\hat{\mathcal{T}}$
- 6: **else**
- 7:     choose  $s \in \mathcal{S}$  such that  $\mathcal{S}$  does not contain a proper divisor of it
- 8:      $\hat{\mathcal{T}} \leftarrow \hat{\mathcal{T}} \cup \{s\}$
- 9:     **end if**
- 10: **end loop**

**Prop:**  $\mathcal{T}$  possesses weakly involutive completions,  $L$  constructive  $\implies$  algorithm terminates with a weakly involutive completion  $\hat{\mathcal{T}}$

**(Sketch of) Proof:**

- *Correctness* obvious: upon termination  $\hat{\mathcal{T}}$  locally involutive
- *Termination* proof very technical: use continuity of  $L$  to show that *each* added term lies in *any* involutive completion of  $\mathcal{T}$  as otherwise contradiction to constructivity of  $L$

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- existence of (weakly) involutive completion must be *assumed*
  - very different to standard *Gröbner* theory (termination implies existence of basis!)
  - no issue for *Noetherian* division like Janet
- termination proof implies surprising properties of output
  - $\mathcal{T}_L$  any weakly involutive completion of  $\mathcal{T} \implies \hat{\mathcal{T}} \subseteq \mathcal{T}_L$
  - output *independent* of choices in Line 7 (simple way to implement choice: use term order)
- natural choice for input: *minimal* basis of  $\langle \mathcal{T} \rangle$  (will see later  $\rightsquigarrow$  yields *minimal involutive basis*)
- recall: simple elimination process yields *strong* involutive basis

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**Lemma:**  $\mathcal{B}$  *minimal* basis of  $\langle \mathcal{T} \rangle$ ,  $L = P$  *Pommaret* division  $\implies$  no termination, if at some stage  $\deg \hat{\mathcal{T}} > \deg \text{lcm } \mathcal{B}$

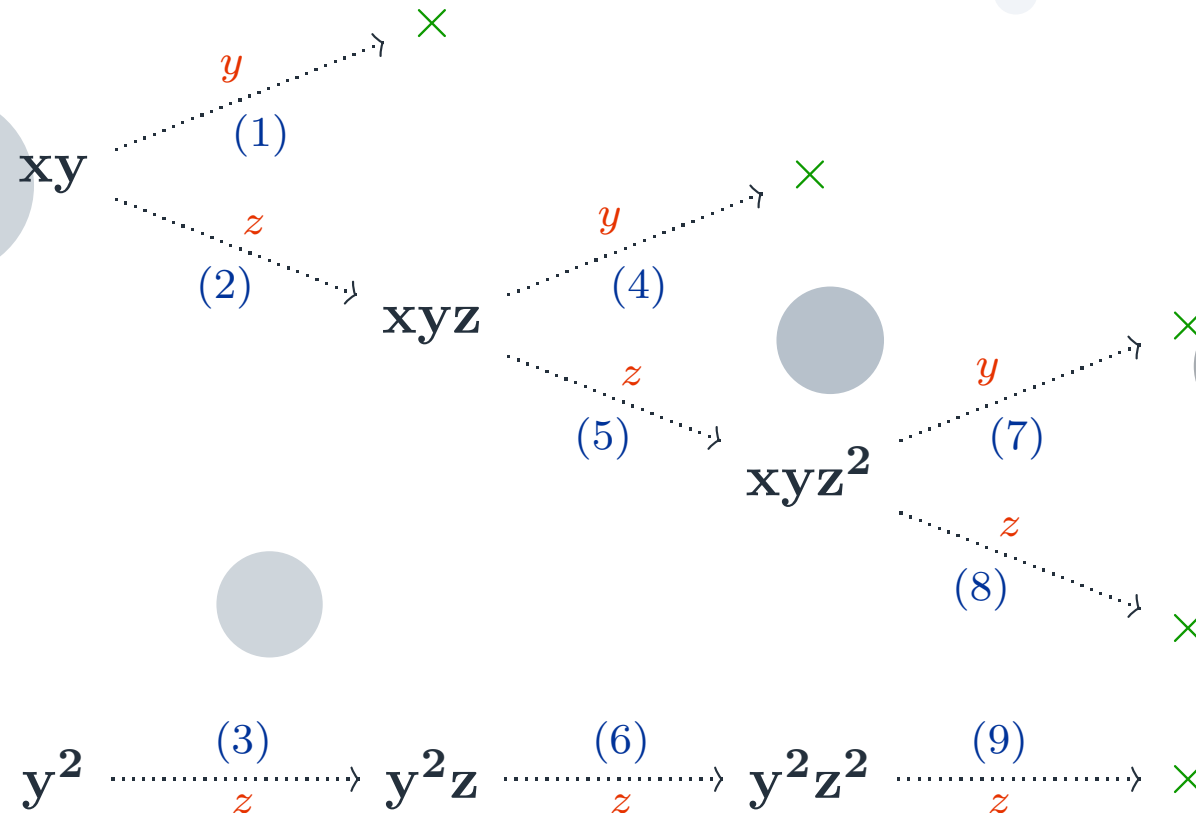
**Proof:** consequence of syzygy theory in Lecture 5



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**Example:**  $\mathcal{T} = \{z^3, y^2, xy\}$  with Pommaret division  
(choose in each iteration  $yt$  minimal for  $\text{degrevlex}$ )



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Given finite polynomial set  $\mathcal{F} \subset \mathcal{P}$ , term order  $\prec$ , involutive division  $L$

## Simplest approach:

- compute *Gröbner* basis  $\mathcal{G}$  of  $\mathcal{I} = \langle \mathcal{F} \rangle$  (e. g. with Buchberger algorithm)  
     $\rightsquigarrow$  leading terms  $\text{Lt } \mathcal{G}$  generate leading ideal  $\text{Lt } \mathcal{I}$
- apply *monomial* completion algorithm to  $\text{Lt } \mathcal{G}$   
(keeping full polynomials!)
- obtain (weakly) *involutive* basis  $\mathcal{H} \supseteq \mathcal{G}$  of  $\mathcal{I}$

Given finite polynomial set  $\mathcal{F} \subset \mathcal{P}$ , term order  $\prec$ , involutive division  $L$

## Better approach:

- generalise *monomial* completion algorithm
  - requires two subalgorithms
    - $\text{NormalForm}_{L,\prec}(g, \mathcal{H})$   
involutive normal form of polynomial  $g \in \mathcal{P}$  wrt finite set  $\mathcal{H} \subset \mathcal{P}$
    - $(\text{Head})\text{AutoReduce}_{L,\prec}(\mathcal{H})$   
involutive (head) autoreduction of finite set  $\mathcal{H} \subset \mathcal{P}$
- (obtained by obvious modifications of standard algorithms)

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## Basic polynomial completion algorithm

**Input:** finite set  $\mathcal{F} \subset \mathcal{P}$ , term order  $\prec$ , involutive division  $L$

**Output:** involutive basis  $\mathcal{H}$  of  $\mathcal{I} = \langle \mathcal{F} \rangle$  wrt  $L$  and  $\prec$

```
1:  $\mathcal{H} \leftarrow \text{HeadAutoReduce}_{L, \prec}(\mathcal{F})$ 
2: loop
3:    $\mathcal{S} \leftarrow \{yh \mid h \in \mathcal{H}, y \in \bar{X}_{L, \mathcal{H}, \prec}(h), yh \notin \langle \mathcal{H} \rangle_{L, \prec}\}$ 
4:   if  $\mathcal{S} = \emptyset$  then
5:     return  $\mathcal{H}$ 
6:   else
7:     choose  $\bar{g} \in \mathcal{S}$  such that  $\text{lt } \bar{g} = \min_{\prec} \mathcal{S}$ 
8:      $g \leftarrow \text{NormalForm}_{L, \prec}(\bar{g}, \mathcal{H})$ 
9:      $\mathcal{H} \leftarrow \text{HeadAutoReduce}_{L, \prec}(\mathcal{H} \cup \{g\})$ 
10:  end if
11: end loop
```

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**Theorem:** division  $\mathcal{L}$  constructive and Noetherian  $\implies$  algorithm terminates with involutive basis  $\mathcal{H}$  of  $\mathcal{I}$

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**(Sketch of) Proof:**

- extend notion of *locally involutive set* to polynomial sets
- show that for continuous division any locally involutive and *involutively head autoreduced* set is involutive
- Noetherian argument shows that leading ideal  $\langle \text{lt } \mathcal{H} \rangle$  stabilises
- then polynomial completion reduces (more or less) to monomial completion

**Theorem:** division  $\mathcal{L}$  constructive and Noetherian  $\implies$   
algorithm terminates with involutive basis  $\mathcal{H}$  of  $\mathcal{I}$

## Some comments:

- it does *not* suffice to assume existence of involutive basis of  $\mathcal{I}$   $\rightsquigarrow$   
we need existence of involutive bases for *all subideals* of  $\text{lt } \mathcal{I}$
- choice in Line 7 corresponds to *normal selection strategy*  $\rightsquigarrow$   
use important for *termination* proof
- even if algorithm does *not* terminate, it always produces for term orders of  
type  $\omega$  a *Gröbner* basis after a *finite* number of steps
- algorithm implicitly reduces *S-polynomials*
- algorithm usually more efficient than *Buchberger algorithm*
  - *Buchberger criteria* to large extent *automatically “built-in”*
  - implicitly *“Hilbert driven”*  
(without a priori knowledge of Hilbert function!)

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**Example:**  $\mathcal{P} = \mathbb{k}[x, y]$ , Pommaret division  $P$

$$\mathcal{F} = \{ \mathbf{f}_1 = y^2 \mathbf{e}_1, \mathbf{f}_2 = xy \mathbf{e}_1 + \mathbf{e}_2, \mathbf{f}_3 = x \mathbf{e}_2 \} \subset \mathcal{P}^2$$



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- choose term order such that  $xy \mathbf{e}_1 \succ \mathbf{e}_2 \rightsquigarrow$   
 $\langle \text{lt } \mathcal{F} \rangle$  has *no* finite Pommaret basis (consider  $\mathbf{e}_2$ -component)
- add  $S$ -“polynomial”  $S(\mathbf{f}_1, \mathbf{f}_2) = y \mathbf{e}_2 = \mathbf{f}_4 \rightsquigarrow$

$$\mathcal{H} = \mathcal{F} \cup \{ \mathbf{f}_4 \} \text{ finite Pommaret basis of } \langle \mathcal{F} \rangle$$

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- termination of completion algorithm depends on properties of term order
  - take “*POT*” order with  $s \mathbf{e}_1 \succ t \mathbf{e}_2$  for arbitrary  $s, t \in \mathbb{T}(x, y)$   
 $\implies$  *no termination*
  - take “*TOP*” order based on degree compatible order  $\rightsquigarrow$   
after finite number of iterations  $\mathbf{f}_4$  is found  $\implies$  *termination*

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**Def:**  $\mathcal{I} \subseteq \mathcal{P}$ ,  $\mathcal{H} \subset \mathcal{I}$  involutive basis

- $\mathcal{H}, \mathcal{I}$  monomial;  $\mathcal{H}$  *minimal involutive basis* of  $\mathcal{I}$   $\rightsquigarrow$   
every monomial involutive basis  $\hat{\mathcal{H}}$  of  $\mathcal{I}$  satisfies  $\mathcal{H} \subseteq \hat{\mathcal{H}}$
- $\mathcal{H}, \mathcal{I}$  polynomial;  $\mathcal{H}$  *minimal involutive basis* of  $\mathcal{I}$   $\rightsquigarrow$   
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 $\text{lt } \mathcal{H}$  minimal involutive basis of  $\text{lt } \mathcal{I}$

**Prop:**  $\mathcal{I} \subset \mathcal{P}$  monomial ideal with involutive basis  $\implies$   
minimal involutive basis exists and obtained by applying monomial completion  
algorithm to minimal basis in ordinary sense

**Prop:**  $L$  globally defined division  $\implies$   
monomial involutive basis unique and thus minimal

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**Example:**  $\mathcal{F} = \{x, x^2\} \subset \mathbb{k}[x]$

$\mathcal{F}$  Janet autoreduced ( $x$  non-mult. for  $x$  because of  $x^2$ )  $\implies$   
 algorithms will leave  $\mathcal{F}$  unchanged

obviously:  $\{x\}$  minimal involutive basis of  $\langle \mathcal{F} \rangle$

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 $\text{lt } \mathcal{H}$  minimal involutive basis of  $\text{lt } \mathcal{I}$

**Prop:** monic, involutively autoreduced, minimal involutive basis unique

**Prop:**  $L$  constructive, Noetherian division  $\implies$   
every polynomial ideal  $\mathcal{I} \subseteq \mathcal{P}$  has minimal involutive basis

**Proof:** optimised completion algorithm

## Algorithm for minimal involutive basis (“ $\mathcal{T}$ - $\mathcal{Q}$ algorithm”)

**Input:** finite set  $\mathcal{F} \subset \mathcal{P}$ , term order  $\prec$ , involutive division  $L$

**Output:** minimal involutive basis  $\mathcal{H}$  of  $\mathcal{I} = \langle \mathcal{F} \rangle$  wrt  $L$  and  $\prec$

```

1:  $\mathcal{T} \leftarrow \emptyset$ ;  $\mathcal{Q} \leftarrow \mathcal{F}$ 
2: repeat
3:    $g \leftarrow 0$ 
4:   while  $(\mathcal{Q} \neq \emptyset) \wedge (g = 0)$  do
5:     choose  $f \in \mathcal{Q}$  such that  $\text{lt } f = \min_{\prec} \mathcal{Q}$ 
6:      $\mathcal{Q} \leftarrow \mathcal{Q} \setminus \{f\}$ ;  $g \leftarrow \text{NormalForm}_{L, \prec}(f, \mathcal{T})$ 
7:   end while
8:   if  $g \neq 0$  then
9:      $\mathcal{T}' \leftarrow \{h \in \mathcal{T} \mid \text{lt } g \prec \text{lt } h\}$ ;  $\mathcal{T} \leftarrow (\mathcal{T} \setminus \mathcal{T}') \cup \{g\}$ 
10:     $\mathcal{Q} \leftarrow \mathcal{Q} \cup \mathcal{T}' \cup \{yh \mid h \in \mathcal{T}, y \in \bar{X}_{L, \mathcal{T}, \prec}(h)\}$ 
11:   end if
12: until  $\mathcal{Q} = \emptyset$ 
13: return  $\mathcal{T}$ 

```

**Theorem:** division  $\mathcal{L}$  constructive and Noetherian  $\implies$   
algorithm terminates with minimal involutive basis  $\mathcal{H}$  of  $\mathcal{I}$

**Proof:**

- *termination* proof requires only slight modifications
- $\mathcal{H}$  *involutive* basis essentially as before
- proof of *minimality* requires analysis of last time a generator is moved to  $\mathcal{H}$



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- *termination* proof requires only slight modifications
- $\mathcal{H}$  *involutive* basis essentially as before
- proof of *minimality* requires analysis of last time a generator is moved to  $\mathcal{H}$

**Example:**  $\mathcal{F} = \{x, x^2\} \subset \mathbb{k}[x]$ , Janet division

- 1. iteration:**  $\mathcal{T} = \{x\}, \quad \mathcal{Q} = \{x^2\}$
- 2. iteration:**  $\mathcal{T} = \{x\}, \quad \mathcal{Q} = \emptyset$

# Optimisations and Complexity Issues

*It's easy to implement a completion algorithm,  
but difficult to provide a good implementation!*

- *worst case* complexity of **any** algorithm for Gröbner bases is *doubly exponential*  $\rightsquigarrow$  potential size of basis (sharp estimate!)
- fortunately in practice rarely realised  $\rightsquigarrow$  “geometric” ideals have usually a lower *Castelnuovo-Mumford regularity* (see Lecture 5)
- good implementations require many *optimisations* of basic algorithms (proof of correctness often much more difficult)
- often only *heuristic* statements possible  $\rightsquigarrow$  good implementations provide *options* to control behaviour of algorithms
- important example: *selection strategy*

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## “Involutive Buchberger criteria”

- try to *predict* that a non-multiplicative product  $yh$  (involutively) reduces to 0 (reductions are the most expensive part of a completion!)
- here much less an issue than for *Buchberger algorithm*
  - ↪ yields only a modest gain in computation time
- to a large extent automatically built-in in our completion algorithm
  - ↪ consequence of *syzygy theory* (Lecture 5)

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**Remark:** “value” of reductions to 0 depends on application context:

- we only need *some* Gröbner basis for, say, deciding an ideal membership problem ↪ such reductions a waste of time
- we also need *syzygy module* (common in algebraic geometry) ↪ (some) reductions to 0 yield valuable information on syzygies (Schreyer theorem — see Lecture 5)

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## “Involutive trees”

- **Problem:** fast determination of *multiplicative variables* for generators and fast search for *involutive divisors* important for efficient completion
- most studied for *Janet division*
- natural *tree structure* on subsets  $(d_k, \dots, d_n) \subset \mathcal{T}$  used for definition of Janet division induced by inclusion relation  $\rightsquigarrow$   
leaves are elements of  $\mathcal{T}$
- leads to special relationship with *lexicographic order* (leaves appear automatically sorted)
- refined version based on *binary trees*
- yields efficient *graph theoretic* algorithms (also for *maintaining* tree during completion!)

## “Good Book-Keeping”

- keep track of *history* of generators in order to avoid redundancies
  - **Example:** for Pommaret division in  $\mathbb{k}[x, y, z]$   
current basis contains  $f \in \mathbb{k}[x]$   $\rightsquigarrow$  must treat  $yf$  and  $zf$   $\rightsquigarrow$   
assume both polynomials must be added unchanged to basis  
(both of class 1)  $\rightsquigarrow$  must later treat *both*  $z(yf)$  and  $y(zf)$
  - in  $\mathcal{T}$ - $\mathcal{Q}$  algorithm for minimal basis generator may repeatedly move between  $\mathcal{T}$  and  $\mathcal{Q}$   $\rightsquigarrow$  record which non-multiplicative products have already been considered
- allows for simple extraction of *reduced Gröbner basis* (without any further computations!)

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## “Intermediate Expression Swell”

**Problem:** in- and output *small*, but intermediate results very *large*  
(quite common in computer algebra)

**Example:** (Arnold)  $\mathcal{P} = \mathbb{Q}[x, y, z]$ , degrevlex

$$\begin{aligned} f_1 &= 8y^2z^2 + 5y^3z + 3xz^3 + xyz^2 & f_3 &= 8z^3 + 12y^3 + x^2z + 3 \\ f_2 &= z^5 + 2x^2y^3 + 13x^3y^2 + 5x^4y & f_4 &= 7y^4z^2 + 18x^2y^3z + x^3y^3 \end{aligned}$$

reduced Gröbner basis of  $\mathcal{I} = \langle f_1, f_2, f_3, f_4 \rangle$

$$g_1 = z \quad g_2 = y^3 + 1/4 \quad g_3 = x^2$$

intermediate polynomials have coefficients with about **80.000** digits

Janet basis requires additionally:  $g_4 = x^2y$ ,  $g_5 = x^2y^2$

largest intermediate coefficients have about **400** digits