## From equations to points: Eigenvalues and Eigenvectors Multiplication map

As before, let K be a field, let  $P = K[x_1, \ldots, x_n]$ , and let  $f_1, \ldots, f_s \in P$ , let  $\overline{K}$  be the algebraic closure of K, and let  $\overline{P} = \overline{K}[x_1, \ldots, x_n]$ . By S we denote the system of polynomial equations

$$\begin{cases} f_1(x_1,\ldots,x_n)=0\\ \vdots\\ f_s(x_1,\ldots,x_n)=0 \end{cases}$$

By *I* we denote the ideal  $(f_1, \ldots, f_s)$ , by *A* the quotient ring P/I, and by  $\overline{A}$  the quotient ring  $\overline{P}/I\overline{P}$ . As usual we assume that *I* is zero-dimensional so that *A* is a finite dimensional *K*-vector space by the Finiteness Criterion.

#### Definition

Given a polynomial  $f \in P$  we consider the following K-linear map  $m_f : A \longrightarrow A$  defined by  $m_f(g \mod I) = fg \mod I$ , and call it the multiplication map defined by f. We also consider the induced K-linear map on the dual spaces  $m_f^* : A^* \longrightarrow A^*$  defined by  $m_f^*(\varphi) = \varphi \circ m_f$ .

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### From equations to points: Eigenvalues and Eigenvectors

### A first example

#### Example

- Let  $P = \mathbb{R}[x]$ ,  $f = x^2 + 1$ , *I* the ideal generated by the polynomial  $x^3 x^2 + x 1 = (x 1)(x^2 + 1)$ , and A = P/I.
- We consider the multiplication map  $m_f : A \longrightarrow A$  and describe it via its representation with respect to the  $\mathbb{R}$  -basis of A given by  $(1, x, x^2)$ .
- Using the relations  $x^3 + x = x^2 + 1 \mod I$ ,  $x^4 + x^2 = x^2 + 1 \mod I$ , we deduce that the matrix which represents  $m_f$  is

### $\begin{pmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 1 & 1 & 1 \end{pmatrix}$

- It is singular, hence 0 is an eigenvalue. Moreover,  $\mathcal{Z}(I) = \{1, i, -i\}$ , and we see that 0 = f(i) = f(-i), but  $\mathcal{Z}_{\mathbb{R}}(I) = \{1\}$  and  $0 \neq f(1)$ .
- Next theorem makes an important link between  $\mathcal{Z}(I)$  and eigenvalues, and the example motivates the reason why we need the assumption that  $\mathcal{Z}_{\mathcal{K}}(I) = \mathcal{Z}(I)$ .

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#### From equations to points: Eigenvalues and Eigenvectors

### **Eigenvalues**

#### Theorem

Proof.

Let I be a zero-dimensional ideal in P such that  $\mathcal{Z}_{K}(I) = \mathcal{Z}(I)$ , let  $f \in P$ , and let  $\lambda \in K$ . The following conditions are equivalent

- The element  $\lambda$  is an eigenvalue of  $m_f$ .
- **2** There exists a point  $p \in \mathcal{Z}(I)$  such that  $\lambda = f(p)$ .

Let id:  $A \longrightarrow A$  denote the identity map. We know that  $\lambda$  is an eigenvalue of  $m_f$  if and only if  $m_f - \lambda$  id is not invertible. Let us prove  $(1) \implies (2)$ . If  $\lambda$  does not coincide with any of the values of f at the points  $p \in \mathbb{Z}(I)$ , then the ideal  $J = I + (f - \lambda)$  has the property that  $\mathbb{Z}(J) = \emptyset$ . On the other hand the ideal J is defined over K, hence the Weak Nullstellenzatz implies that  $1 \in J$ . It means that there exists  $g \in P$  such that  $1 = g(f - \lambda) + h$  with  $h \in I$ . Then  $1 = g(f - \lambda)$  mod I, so that  $m_f - \lambda$  id is invertible with inverse  $m_g$ , and hence  $\lambda$  is not an eigenvalue of  $m_f$ . This finishes the proof of  $a) \Longrightarrow b$ , Let us prove  $(2) \Longrightarrow (1)$ . If  $\lambda$  is not an eigenvalue of  $m_f$ , then  $m_f - \lambda$  id is an invertible map, in particular it is surjective. So, there exists  $g \in P$  such that  $g(f - \lambda) = 1 \mod I$ . Clearly this implies that there cannot exist  $p \in \mathbb{Z}(I)$  such that  $f(p) - \lambda = 0$ 

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# From equations to points: Eigenvalues and Eigenvectors The matrix $M_{fE}^E$

- If E = (t<sub>1</sub>,..., t<sub>µ</sub>) is a row of polynomials whose residue classes form a K -basis of A = P/I, then we use the short form fE to mean the row of vectors (ft<sub>1</sub>,..., ft<sub>µ</sub>).
- A way of describing  $m_f$  explicitly is to fix such a K-basis E of A and represent  $m_f$  via the matrix  $M_{fE}^E$  where the j-column of  $M_{fE}^E$  is given by the coefficients of  $ft_j$  when written in terms of E. In other words, if

$$ft_j = \sum_{k=1}^{\mu} a_{kj} t_k \mod k$$

then the  $j^{\text{th}}$  column of  $M_{fE}^{E}$  is  $(a_{1j}, a_{2j}, \ldots, a_{\mu j})^{\text{tr}}$ . A more compact way of expressing this fact is the following formula

$$fE = E M_{fE}^E \mod M_{fE}$$

 Usually a K -basis E is an order ideal of monomials and hence we may assume that t<sub>1</sub> = 1. We may as well assume that the residue classes of some of the indeterminates (most of the times all) are among the entries of E.

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#### From equations to points: Eigenvalues and Eigenvectors Eigenvalues and coordinates of zeros

#### Corollary

Let  $x_i$  be such that its class is among the entries of E. Then the  $x_i$  coordinates of the points in  $\mathcal{Z}_{K}(I)$  are the eigenvalues of  $m_{x_i}$ .

#### Proof.

It follows immediately from the theorem, since  $x_i(p)$  is exactly the  $x_i$  coordinate of p.

We observe that, as in the case of the Lex-method, we need the zeros of a polynomial (in this case the characteristic polynomial), and hence we hit again an intrinsic obstacle: we need approximation.

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The above corollary gives a first method for computing  $\mathcal{Z}_{\mathcal{K}}(I)$ , however what we get is only a grid of points which is usually a much larger set than  $\mathcal{Z}_{\mathcal{K}}(I)$ . Sometimes we can do better, but we need a description of eigenvectors. In the sequel we use the following terminology.

# From equations to points: Eigenvalues and Eigenvectors Eigenvectors and coordinates of zeros

#### Definition

Let  $\varphi: V \longrightarrow V$  be a linear map of K-vector spaces, let  $\lambda \in K$  be an eigenvalue of  $\varphi$ , and let  $W_{\lambda} = \text{Ker}(\varphi - \lambda \operatorname{id})$  be the corresponding eigenspace. Then the non-zero vectors in  $W_{\lambda}$  are called  $\lambda$ -eigenvectors, or simply eigenvectors, if the context is clear.

### Corollary (Eigenvectors)

Let  $p \in \mathcal{Z}_{K}(I)$ , and let  $E = (t_{1}, \ldots, t_{\mu})$  be a row of power products whose classes form a K-basis of A. Then the vector  $E(p) = (t_{1}(p), \ldots, t_{\mu}(p))$  is an f(p)-eigenvector of  $m_{t}^{*}$ .

Proof.		
We use the formula $fE = E M_{fE}^E \mod I$ and evaluate both sides at $p$ . We get		
$f(p)E(p) = E(p) M_{fE}^{E}$		
By transposing both sides we get $t(\rho)(E(\rho))^{\rm tr} = (M_{fE}^{E})^{\rm tr} (E(\rho))^{\rm tr}$		
This formula means that $E(p)$ is an $f(p)$ -eigenvector of the matrix $(M_{fE}^{E})^{tr}$ , hence of $m_{f}^{*}$ .		
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# From equations to points: Eigenvalues and Eigenvectors Non-derogatory matrices I

### Definition

A square matrix  $M \in Mat_{\mu}(\mathbb{C})$  is said to be non-derogatory if the following equivalent conditions are satisfied.

- All eigenspaces of M are 1 -dimensional.
- **2** The Jordan canonical form of M has one Jordan block per eigenvalue.
- MinPoly<sub>M</sub> = CharPoly<sub>M</sub>.

Next corollary is one of the many variations which can be played around the above result. It highlights the importance of non-derogatory matrices.

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## From equations to points: Eigenvalues and Eigenvectors Non-derogatory matrices II

#### Corollary

Let  $1, x_1, \ldots, x_n$  be the first n + 1 -entries of E, assume that the matrix  $(M_{fE}^E)^{tr}$  is non-derogatory, let  $\mathcal{Z}_K(I) = \mathcal{Z}(I) = \{p_1, \ldots, p_r\}$ , and let  $W_1, \ldots, W_r$  be the 1-dimensional eigenspaces corresponding to  $f(p_1), \ldots, f(p_r)$  respectively. If we choose  $v_j = (a_{1j}, a_{2j}, \ldots, a_{r+1,j}, \ldots) \in W_j \setminus 0$ , for  $j = 1, \ldots, r$ , then we have the equalities  $p_j = (a_{2j}/a_{1j}, \ldots, a_{r+1,j}/a_{1j})$  for  $j = 1, \ldots, r$ .

#### Proof.

We use the above corollary about eigenvectors to deduce that the vector  $E(p_j) = (t_1(p_j), \ldots, t_{\mu}(p_j))$  is an  $f(p_j)$ -eigenvector of f, hence it is a non-zero vector in  $W_j$  for  $j = 1, \ldots, r$ .

The assumption about  $(M_{fE}^E)^{tr}$  means that all the  $W_j$ 's are 1-dimensional vector spaces, hence the vectors  $E(p_j)$  and  $v_j$  are proportional.

On the other hand, we know that  $t_1 = 1$ , hence  $t_1(p_j) = 1$ , hence  $a_{1j} \neq 0$ . We divide the coordinates of  $v_j$  by  $a_{1j}$  and conclude.

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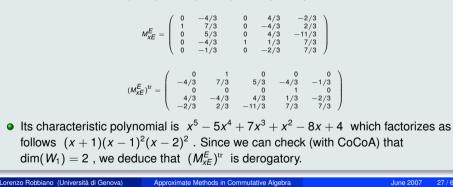
We observe that the computation of eigenspaces creates a new difficulty. Since the eigenvalues are in general given up to a certain degree of accuracy, the eigenspaces are not computable as kernels of linear maps.

#### From equations to points: Eigenvalues and Eigenvectors

### Example I

#### Example

- Let *I* be the ideal in  $P = \mathbb{R}[x, y]$  generated by the set of polynomials { $x^2 + 4/3xy + 1/3y^2 - 7/3x - 5/3y + 4/3$ ,  $y^3 + 10/3xy + 7/3y^2 - 4/3x - 20/3y + 4/3$ ,  $xy^2 - 7/3xy - 7/3y^2 - 2/3x + 11/3y + 2/3$ }.
- We can check that this set is a DegRevLex-Gröbner basis, hence  $E = [1, x, y, xy, y^2]$  is a basis modulo I.
- By computing  $NF(x^2, I)$ ,  $NF(x^2y, I)$ ,  $NF(xy^2, I)$ , we get



# From equations to points: Eigenvalues and Eigenvectors Example II

### Example (continued)